CCSU DEPARTMENT OF MATHEMATICAL SCIENCES

COLLOQUIUM

Tuesday, October 19 12:30 – 1:30 PM Maria Sanford, Room 101

ROBOT MOTION PLANNING

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ABSTRACT

What is the space of all possible ways robots can move in a room? What happens when we place obstacles in their path? We not only look at the important subject of robot motions but look at the ideas behind robot collisions. This leads to worlds of polyhedra, tilings, string theory, and phylogenetic trees. During this adventure, we visually learn what multiplication is really about as well as learning to draw in higherdimensions. This talk is heavily based on pictures and no background is needed.

For further information:

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