

CCSU
DEPARTMENT OF MATHEMATICAL SCIENCES
COLLOQUIUM

Friday, March 1
2:00 – 3:00 PM
Maria Sanford, Room 101

**A CHARACTERIZATION OF QUADRIC
CONSTANT SCALAR CURVATURE HYPERSURFACES OF SPHERES**

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Abstract: Let $S^4 = \{x \in \mathbb{R}^5 : |x|=1\}$ be the unit 4-dimensional sphere. Easy examples to define in this manifold are $M_1(c) = \{(x_1, x_2, x_3, x_4, x_5) \in S^4 : x_5 = c\}$ where $c \in (-1, 1)$ and $M_2(r) = \{(x_1, x_2, x_3, x_4, x_5) \in S^4 : x_4^2 + x_5^2 = r^2\}$ where $r \in (0, 1)$. It is not difficult to see that $M_1(c)$ is a 3-dimensional sphere with radius $(1-c^2)^{1/2}$ and $M_2(r)$ is the Cartesian product of a circle of radius r and a 2-dimensional sphere of radius $(1-r^2)^{1/2}$. Up to rigid motions, a quadratic hypersurface in S^4 is a hypersurface that can be written as $M_2(r)$ for some r . Due to its large group of symmetries, both families of hypersurfaces $M_1(c)$ and $M_2(r)$ have constant scalar curvature.

Let us consider a hypersurface $M \subset S^4$. For every point $x \in M$, the tangent space $T_x M$ is a three dimensional space in \mathbb{R}^5 which can be shown is perpendicular to the vector x . Therefore, the vector space

$$W(x) = \{v + \lambda x : v \in T_x M, \lambda \in \mathbb{R}\}$$

is a 4-dimensional space of \mathbb{R}^5 . By basic linear algebra we know that up to a sign, there exists a unique vector $N(x)$ in \mathbb{R}^5 that is perpendicular to the vector space $W(x)$. When M is orientable, we can choose a continuous function $N: M \rightarrow \mathbb{R}^5$, such that $N(x)$ has norm 1 and $N(x)$ is perpendicular to $W(x)$. This map is called a Gauss map. In this talk we will present the following result

Theorem (Perdomo-Wei, to appear in the Journal of Geometric Analysis): Let $M \subset S^4$ is a complete (topologically complete space) orientable hypersurface with constant scalar curvature and let $N: M \rightarrow \mathbb{R}^5$ be its Gauss map. If for some fixed vector $v \in \mathbb{R}^5$ and some real number λ , we have

$$\langle N(x), v \rangle = \lambda \langle x, v \rangle \text{ for all } x \in M$$

then, up to a rigid motion, M is equal to either $M_1(c)$ for some c or $M_2(r)$ for some r . (Here $\langle u, w \rangle = u_1 w_1 + u_2 w_2 + u_3 w_3 + u_4 w_4 + u_5 w_5$ is the standard inner product in \mathbb{R}^5 .)

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